

# SITM: Robotic Assisted Gynaecological Surgery (RAGS)

# **SECTION 1: CAPABILITIES IN PRACTICE**

| RAGS CiP 1: The doctor can be an effective assistant within the multidisciplinary robotic surgical team            |   |  |  |  |  |
|--|---|--|--|--|--|
| Key Skills   | Descriptors   |  |  |  |  |
| Familiarity with robotic<br>components,<br>instrumentation, mechanics,<br>ergonomics and fundamental<br>techniques | <ul> <li>Knowledge of the operative room setup for the robotic system.</li> <li>Can correctly position the patient for robotic surgery.</li> <li>Undertakes vaginal preparation for a robotic procedure.</li> <li>Aware of principles of the robotic system and the fundamentals of the robotic system components and instrumentation.</li> <li>Able to drape the robot.</li> <li>Able to respond to system errors.</li> <li>Able to drive the robot.</li> <li>Can maintain a clear image by cleaning/changing the camera.</li> <li>Able to insert, change and remove robotic instruments.</li> <li>Can trouble shoot and re-dock the robotic system.</li> <li>Able to undertake port placement.</li> <li>Understand different docking positions and able to dock the robot in different positions.</li> <li>Demonstrates use of suction and maintaining clear operative field</li> <li>Able to introduce and present loaded needle.</li> <li>Understands and can demonstrate use of different methods of maintaining pneumoperitoneum.</li> <li>Can safely retrieve needle/ swabs/specimen.</li> </ul> |  |  |  |  |
| Safely uses energy sources as part of robotic surgery  | <ul> <li>Uses correct energy type and setting for each procedure.</li> <li>Takes steps to prevent diathermy related complications Is aware of mechanism of using various energy modalities.</li> <li>Is aware of mechanism of using various energy modalities.</li> </ul>   |  |  |  |  |
| Works effectively as part of the multidisciplinary team  | <ul> <li>Appreciates the impact of human factors on the functioning of the team and the safety of the surgery.</li> <li>Provides leadership within the team.</li> <li>Communicates clearly with the theatre and anaesthetic team</li> <li>Demonstrates understanding of specimen handling and histology/cytology requests.</li> <li>Demonstrate skills of communication with recovery and ward staff.</li> </ul>  |  |  |  |  |



| <ul> <li>Instructs nursing staff on postoperative care and pain management.</li> <li>Ensure thromboprophylaxis type, dose and duration is communicated to postoperative teams and patient.</li> </ul>  |  |  |  |  |  |
|--|--|--|--|--|--|
| Evidence to inform decision  |  |  |  |  |  |
| <ul> <li>Reflective practice</li> <li>TO2</li> <li>Direct observation by senior colleagues</li> <li>Attendance at Local, Deanery and National teaching</li> <li>Completed online training module for robotic system</li> <li>Attendance at a local, regional, national robotic courses</li> </ul>  | <ul> <li>Confirmed participation in<br/>multidisciplinary team meetings and<br/>clinics</li> <li>Leads critical incident review</li> <li>OSATS:         <ul> <li>Docking/Undocking</li> </ul> </li> <li>CbD</li> <li>Mini-CEX</li> <li>TO2 (including SO)</li> </ul> |  |  |  |  |
| Knowledge criteria   |  |  |  |  |  |
| <ul> <li>Demonstrates understanding fundamental instrumentation</li> <li>Understanding of the use of energy sources in used inappropriately</li> <li>Demonstrate understanding of communication</li> <li>Relevant anatomy and robotic interferences</li> <li>Understands indications for robotic surgery ind</li> <li>Informed consent</li> <li>Effects of pneumoperitoneum</li> <li>Be able to understand reasons for robot arm c</li> <li>Understand the appropriate use of assistant point</li> </ul> | s of the robotic system components and<br>n robotic surgery and its potential complications if<br>n with scrub team and needle/swab count<br>cluding:<br>lashing and adjust the arm positions<br>ort   |  |  |  |  |

- Understands neurological conditions that could be due to poor positioning during prolong procedure
- Objective methods for assessing port placement and pneumoperitoneum

| RAGS CiP 2: The doctor provides high quality surgery for pelvic pathology using robotic assistance. |  |  |  |  |  |
|---|--|--|--|--|--|
| Key Skills  | Descriptors  |  |  |  |  |
| Demonstrates safe surgical practice   | <ul> <li>Selects patient appropriately for robotic surgery with emphasis<br/>on complex patients, high BMI and those with deep pelvic<br/>pathology where robotic assistance will enhance surgery and<br/>recovery.</li> <li>Demonstrate skills to overcome 'Lack of Haptic feedback' with<br/>current robotic surgery.</li> <li>Demonstrate micro dissection and atraumatic tissue handling<br/>with the robotic system.</li> </ul> |  |  |  |  |



|  | <ul> <li>Maintains safety</li> <li>Ale to perform o</li> <li>Able to independ<br/>adhesiolysis.</li> <li>Able to independ</li> <li>Has appropriate<br/>surgery.</li> </ul>  | is safety of the operative field.<br>Prform ovarian or uterine artery ligation.<br>Independently perform laparoscopic /robotic<br>ysis.<br>Independently perform a robotic hysterectomy.<br>Propriate suture handling and knot tying skills for robotic   |  |  |  |  |
|--|---|---|--|--|--|--|
| Evidence to inform decision  |   |   |  |  |  |  |
| <ul> <li>Reflective practice</li> <li>NOTSS</li> <li>Attendance at Risk Management meetings</li> <li>Attendance at skills drill events</li> <li>Completion of online system training</li> <li>Completions of 30hours simulation console training</li> <li>Attendance at robotic course/s</li> </ul>  |   | <ul> <li>OSATS:</li> <li>Docking and undocking</li> <li>Hysterectomy</li> <li>NOTSS</li> <li>CbD</li> <li>Feedback from trainer</li> <li>TO2</li> <li>Mini-CEX</li> </ul>   |  |  |  |  |
| Knowledge criteria   |   |   |  |  |  |  |
| <ul> <li>The necessary robotic equip</li> <li>Potential surgical complicat</li> <li>How to manage major haer</li> <li>The indications and complie</li> <li>Robotic port placement</li> <li>Surgical anatomy of pelvis</li> <li>Alternative treatment optic</li> <li>Demonstrates understanding instrumentation</li> <li>Understanding of the use of used inappropriately</li> <li>Demonstrate understandin</li> <li>Ability to prevent excessive</li> <li>Able to undertake robotic at Surgical management of collar solution</li> <li>Involvement of another special solution of the use of</li></ul> | pment and theatre set<br>tions<br>morrhage<br>cations of robotic pro<br>ons, indications, comp<br>ng fundamentals of th<br>f energy sources in ro<br>g of communication w<br>blood loss during sur<br>issisted suturing<br>mplications & approp<br>ecialist and asking for<br>ncy undocking proceed<br>opy or laparotomy as<br>g of specimen handlir<br>ith recovery and ward | t-up<br>cedures:<br>blications, informed consent<br>he robotic system components and<br>bbotic surgery and its potential complications if<br>with scrub team and needle/swab count<br>rgical procedure<br>briate referral<br>help as required.<br>dure<br>appropriate<br>ing and histology/cytology requests<br>d staff |  |  |  |  |
| RAGS CiP 3: Th <u>e doctor is com</u>  | petent in r <u>ecognising</u>   | , assessing, and managing complications and   |  |  |  |  |

emergencies in robotic theatre.



| Key Skills   | Descriptors   |  |  |  |  |
|--|---|--|--|--|--|
| Recognises, minimises, and<br>manages harm from<br>complications   | <ul> <li>Recognises surgical complications (bowel/urinary/vascular injuries) and involves appropriate specialists.</li> <li>Recognises potential intra-operative risks and makes appropriate operative decisions to mitigate harm.</li> <li>Recognises role of other specialists in the management of surgical complications.</li> <li>Recognises the potential effect of a prolonged pneumoperitoneum.</li> <li>Understands indications for conversion to laparoscopic or open surgery.</li> <li>Demonstrate situational awareness and estimation of blood loss.</li> <li>Demonstrates assessment and management of unstable patient.</li> <li>Able to perform an emergency undocking procedure.</li> <li>Ability to recognises early warning signs in patients on postoperative pathway.</li> <li>Manages postoperative complications and can determine the need for HDU care.</li> </ul> |  |  |  |  |
| Can lead and manage robotic<br>theatre in an emergency   | <ul> <li>Understands the importance of 'Human Factors' in the context of the robotic theatre environment.</li> <li>Manages any complication calmly and requesting early help as and when needed as part of a multidisciplinary team.</li> <li>Implements and directs safe ergonomic positioning in theatre for patient safety.</li> <li>Able to communicate clearly during an emergency with the scrub team, anaesthetic team, and assistants.</li> <li>Safely removes instrument under direct vision.</li> </ul>   |  |  |  |  |
| Evidence to inform decision  |   |  |  |  |  |
| <ul> <li>Evidence of setting up le programme</li> <li>Reflective practice</li> <li>Feedback from trainees and</li> <li>Attend theatre team briefin</li> <li>Attend risk management model</li> </ul>  | <ul> <li>NOTSS</li> <li>CbD</li> <li>Mini-CEX</li> <li>Feedback from trainees</li> <li>ng and WHO check list</li> <li>Local and Deanery Teaching</li> </ul>   |  |  |  |  |
| Knowledge criteria   | f communication with scrub toom and assistant   |  |  |  |  |
| <ul> <li>Onderstands importance of communication with scrub team and assistant</li> <li>Aware of impact of 'Human behaviour' in running of safe theatre list</li> <li>Understand robot system in use of fulfil the requirements before removing instruments</li> <li>Understands how to overcome system error in an emergency</li> <li>Understands the requirements for uninterrupted power supply to robot components</li> <li>Teaching skills and giving clear instructions</li> </ul> |   |  |  |  |  |



- Understands importance of giving precise instructions to assistant to perform arterial clip application for prevention of bleeding
- Able to give supportive constructive feedback to trainees/ assistants
- Has knowledge of how to perform an emergency undocking procedure and communication with team
- Ability to prevent excessive blood loss during surgical procedure
- Effective communication with recovery and ward staff

## **SECTION 2: PROCEDURES**

Procedures marked with \* require three summative competent OSATS

| Procedures                                  | Level by end<br>of training | CIP 1 | CIP 2 | CIP 3 |
|---|-----------------------------|-------|-------|-------|
| Docking and undocking of robot *            | 5                           | Х     | Х     | Х     |
| Robotic assisted Hysterectomy *             | 5                           | Х     | Х     |       |
| Robotic assisted Myomectomy                 | 1                           | Х     |       |       |
| Robotic assisted excision of rectovaginal   | 1                           | Х     |       |       |
| endometriosis                               |                             |       |       |       |
| Robotic assisted Hysterectomy for           | 1                           | Х     |       |       |
| gynaecological cancer +/- LN dissection     |                             |       |       |       |
| Robotic assisted Procedure for pelvic floor | 1                           | Х     |       |       |
| prolapse or incontinence                    |                             |       |       |       |
| Robotic assisted reimplantation of ureter   | 1                           | Х     |       | Х     |

### **SECTION 3: GMC GENERIC PROFESSIONAL CAPABILITIES**

#### Mapping to GPCs

Domain 1: Professional values and behaviours

- Domain 2: Professional skills
  - Practical skills
  - Communication and interpersonal skills
  - Dealing with complexity and uncertainty
  - Clinical skills (history taking, diagnosis and management, consent; humane interventions; prescribing medicines safely; using medical devices safely; infection control and communicable diseases)

Domain 3: Professional knowledge

- Professional requirements
- National legislative requirements
- The health service and healthcare systems in the four countries

Domain 4: Capabilities in health promotion and illness prevention

Domain 5: Capabilities in leadership and teamworking



Domain 6: Capabilities in patient safety and quality improvement

- Patient safety
- Quality improvement

Domain 7: Capabilities in safeguarding vulnerable groups

#### **SECTION 4: MAPPING OF ASSESSMENTS TO RAGS CIPs**

| RAGS CIP   | Online Modules<br>Possible<br>Courses   | OSATS                      | Mini-CEX | CbD | NOTSS | TO1/<br>TO2 | Reflective<br>practice |
|--|---|----------------------------|----------|-----|-------|-------------|------------------------|
| 1: The doctor can be an<br>effective assistant within<br>the multidisciplinary robotic<br>surgical team                            | Online Modules<br>Simulator<br>training<br>certification                            | Simulator<br>Task<br>based | Х        | x   | x     | х           | Х                      |
| 2: The doctor provides high<br>quality surgery for pelvic<br>pathology using robotic<br>assistance                                 | Log book<br>Audit Project<br>Dry lab/Wet lab<br>robotic courses<br>Training courses | X                          | X        | x   | X     | Х           | x                      |
| 3: The doctor is competent<br>in recognising, assessing,<br>and managing<br>complications and<br>emergencies in robotic<br>theatre | Skills<br>drill/robotic<br>courses<br>Human factors/<br>communication<br>course     | X                          | X        |     | Х     | х           | Х                      |